## Grayhill Intuitive Human Interface Solutions

## SERIES 68B Hall Effect Rocker Switch

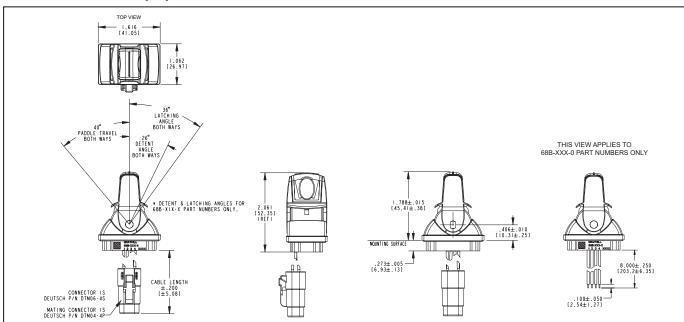
## FEATURES

- Choice of ratiometric analog or PWM outputs
- Sealed to IP67 dynamic even during actuation
- Rugged industrial design suited for outdoor use
- Provides positive tactile feedback in any environment
- · Long operational life
- Redundant output for safety
- Available with 26° detent and 36° latching, friction hold, or spring return (no detent)
- Choices of cable length
- · Choices of accent color

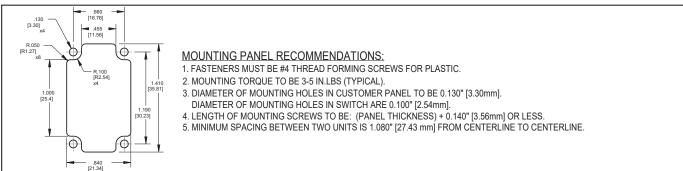
## **APPLICATIONS**

- Dash-panel and armrest controls
- Hydraulic fluid flow control
- Engine speed control
- Heavy duty industrial equipment
- Remote control belly boxes

DIMENSIONS in inches, [mm]

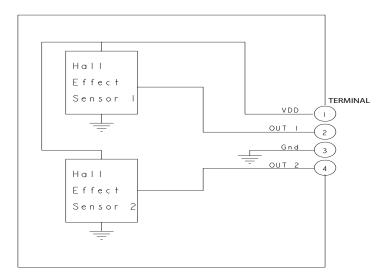


## **MOUNTING PANEL OPTIONS**





### **BLOCK DIAGRAM**



VDD = 5.00V (FOR REFERENCE ONLY)

4.5V

ENSO

PADDLE ANGLE (DEGREES FROM CENTER)

5) 0°

ION

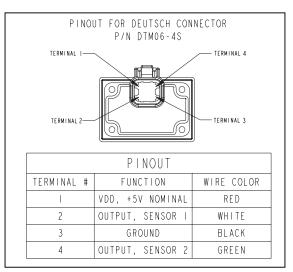
DITPIT

SWITCH

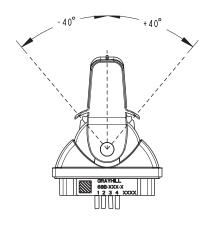
0.0

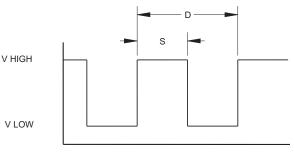
0.5V

## **PINOUT AND WIRE COLOR CHART**



## **POSITIVE/NEGATIVE DIRECTION REFERENCE**





TIME

DUTY CYCLE DEFINED AS THE RATIO BETWEEN THE HIGH TIME (S) AND THE PERIOD (D) OF THE PWM SIGNAL AS SHOWN IN FIGURE ABOVE.

4.5V

@ -40°

0.5V

@ -40°

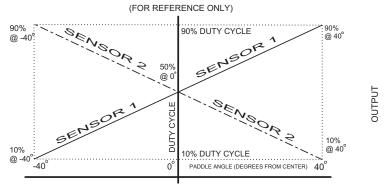
# PWM OUTPUT WAVEFORM

ANALOG OUTPUT WAVEFORM

SENSOR

NOT TO SCALE

<u>40</u>



FAILURE INDICATIONS*			
FAILURE MODE	PWM FR	EQUENCY	DUTY CYCLE
SENSOR ERROR	$50\% \pm$	37.5 Hz	85% OR 95%
OVERVOLTAGE	$50\% \pm$	37.5 Hz	75%
UNDERVOLTAGE	$50\% \pm$	37.5 Hz	100%

\* IN CASE OF ERROR THE SENSOR CHANGES THE PWM FREQUENCY TO 50% OF THE NORMAL OPERATING FREQUENCY 4.5V

@ 40°

0.5V

@ 40°

40

### SPECIFICATIONS

### **Electrical Specifications**

Operating Voltage on Pin 1 (VDD): 5.0V ± 0.5V

Absolute Maximum Voltage\* on Pin 1 (Vbb): -18 V min, +18 V max (t < 1 h) Operating Current: 15 mA typ., 20 mA, max.

### Analog

### Output Voltage is Analog (Ratiometric to Operating Voltage)

Output at Center Position: 50% VDD Output at Full Travel: 10% VDD or 90% VDD depending on configuration

Output Voltage Tolerance:

± 3% VDD at full travel

± 5% VDD at center position

Output Current: 1 mA, max. Recommended Load: 10 K Ohm pull-down resistor.

**Sensor Error:** When a sensor error occurs, the output goes to < 4% of operating voltage (VDD )

\*Exceeding the Absolute Maximum Voltage may result in permanent damage to the device. This is a stress rating only and functional operation of the device at those or any other conditions above those indicated in the operation listings of this specification is not implied.

### **PWM**

Time from Power-up to Signal Out: 8mS Max

PWM Frequency Tolerance:  $\pm$  15% Center Position Duty Cycle:  $50 \pm 5\%$ End Position 1 Duty Cycle:  $10 \pm 3\%$ End Position 2 Duty Cycle:  $90 \pm 3\%$ VOL: 0.5V typ. @ I < 5mA; VDD= 5.00V VOH: 4.9V typ. @ I < -1.2mA; VDD= 5.00V Rocommended Load: 1.0 K Ohm pull-up resistor.

### **Physical & Mechanical Ratings**

Vibration: Random, meets MIL-STD-810G. Method 514.6. Procedure I Mechanical Shock: Meets MIL-STD 202, Method 213B Test Condition A Transit Drop: Meets MIL-STD-810G, Method 516.6, Procedure II Terminal Strength: 10 lbs. minimum, tested per MIL-STD-202, Method 211A Push-Out Force: 45 lbs. minimum Pull-Out Force: 45 lbs. minimum Paddle Impact: 0.5 lbs. weight dropped 3x from height of 0.3m Paddle Side-Load: 45 lbs. minimum Mounting Torque: 3-5 in-lbs (Typical) Return to Center Life: 2 million cycles minimum\*\* Detent Life: 200,000 cycles minimum

Latching Life: 200,000 cycles minimum

Friction Hold Life: 200,000 cycles minimum

 $^{**}$  One cycle is defined as full travel from the center to the +40° direction, then full travel to the -40° direction, then return to the center

### **Environmental Ratings**

Seal: IP67 as mounted

Altitude: Meets MIL-STD-810G, Method 500.4, Procedure I

Thermal Shock: Meets MIL-STD-810G, Method 503.4, Procedure I

**Operating High Temperature:** +85°C, Meets IEC 68-2-2, Test Aa

**Operating Low Temperature:** -40°C, Meets IEC 68-2-1, Test Aa

**Storage High Temperature:** +100°C, Meets IEC 68-2-2, Method Aa

**Storage Low Temperature:** -55°C, Meets IEC 68-2-1, Method Aa

Damp Heat Cycle: Meets IEC/EN 60068-2-38 Z/AD

Humidity, 85/85: Meets MIL-STD 202, Method 103B, 500 hours Solar Radiation: Meets ISO 4892-2, Method A, Cycle 1, 1000 hours Chemical Resistance: Meets IEC 60068-2-74 Salt Fog: Meets MIL STD 810G

Dielectric: Meets MIL-STD-202G, Method301 Insulation Resistance: Meets MIL-STD-202G, Method 302

### **Materials and Finishes**

**Paddle:** Thermoplastic with elastomer finger grip

Cable Assembly: 22AWG stranded, tincoated copper wires in PVC insulation Connector Body: Thermoplastic Terminals: Nickel RoHS Compliant

### **EMC Ratings**

**Radiated Immunity:** At 3 orientations, meets ISO11452-5 (140 V/M, 10KHz-2MHz), ANSI/ ASAE EP455 5.16 (100 V/M, 2-200MHz), ISO 11452-2 (140 V/M, 200MHz-1GHz), and ISO 11452-2 (50 V/M, 1GHz-2.7GHz).

Conducted Immunity: Bulk Current Injection Meets ISO11452-4, SAE J1113-4 (120 mA, 1MHz-400MHz)

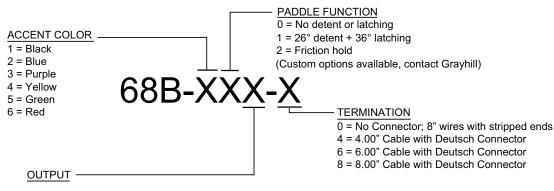
Radiated Emissions: Meets CISPR25, Class 3 (150kHz - 54MHz), CISPR 16.2.3, Class B (30-1000 MHz) and ISO13766, level 6db (30MHz - 1GHz)

Conducted Emissions: Meets CISPR 25, Class 5

**Electrostatic Discharge:** Meets ANSI/ASAE EP455 5.12, Level 1

Power Frequency Magnetic Field: Meets IEC 61000-4-8, 30 A/m

## ORDERING INFORMATION



5 = Analog, 5.0V Supply, Dual Inverse Outputs\*

A = PWM, 5.0V Supply, FREQ. = 500 Hz, Dual Inverse Outputs B = PWM, 5.0V Supply, FREQ. = 2 kHz, Dual Inverse Outputs

**\*OUTPUT VOLTAGE IS PROPORTIONAL TO VDD**